# Single Shot Fault Tolerance <br> I don't know much about it but I don't think it works 

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Coogee Quantum Information Theory Workshop

## Outline

(1) Background
(2) Fault tolerance
(3) Single shot fault-tolerance?

- Random codes
- Sparse codes
- Weaker notion?
(4) Conclusion


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(1) Background
(2) Fault tolerance
(3) Single shot fault-tolerance?

- Random codes
- Sparse codes
- Weaker notion?

4. Conclusion

## An $[n, k, d]$ binary linear codes

- An $(n-k) \times n$ parity check matrix $H$ with binary entries.
- Codewords are the $n$-bit strings $x$ which live in the kernel of $H$ :

$$
\mathcal{C}=\left\{x \in\{0,1\}^{n}: H x=0\right\}
$$

(arithmetic is binary throughout).

- Assuming that the rows of $H$ are linearly independent, there are $2^{k}$ strings in $\mathcal{C}$.
- The shortest non-zero string in $\mathcal{C}$ has weight $d$, and this defines the minimum distance of the code.
- A bit flip error on codeword $x$ produces $y=x+e$.
- The syndrome of $y$ is $s \equiv H y=H(x+e)=H e$.
- The syndrome $s=$ He gives us partial information about $e$ and decoding consists in inferring e from this partial information.


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## Tanner graphs

## Repetition code [7, 1, 7]



## Check nodes Bit nodes

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- Is $6 \times 7$ so $k=1$
- $\mathcal{C}=\{0000000,1111111\}$.
- We see that $d=7$.


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- We can arrange these into the columns of a generating matrix

- The code $\mathcal{C}$ is the image of $G$ :


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## Sparse codes

- A sparse code, or low density parity check (LDPC) code is one whose parity check matrix is row and column sparse.
- There are no more than $\lambda_{r}$ nonzero entries per row.
- There are no more than $\lambda_{c}$ nonzero entries per colmn.

It's easy to recognize an IDPC code from its Tanner graph.

- In a quantum setting, where extracting a syndrome implies actually measuring the corresponding checks, low weight is a blessing!


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## Random codes

- Define the binary entropy $h(p)=-p \log p-(1-p) \log (1-p)$. (Logarithm is base 2)
- Pick the $(n-k) \times k$ binary entries of $H$ at random.
- With very high probability
- By 'correct', we mean that typical errors all have different syndromes, so they can in principle be uniquely identified from their syndrome.
- It is not known how to do this decoding efficiently for random codes.


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4) Conclusion

## Syndrome errors

- For the purpose of this talk, fault tolerance will refer to something very simple:

The syndrome bits are not reliable.

- Bits/qubits are subjected to errors with error-rate p.
- The syndrome $s$ is measured on the corrupted string.
- The syndrome bits are subjected to a bit-flip noise with rate $q$. - We will consider the 'symmetric' case $p=q$ for simplicity.
- This is ofter referred to as the 'phenomenological noise model'
- A more detailed noise model would consider how the syndrome bits are measured and how errors in that measuring circuit propagate.


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- The syndrome bits are subjected to a bit-flip noise with rate $q$.
- We will consider the 'symmetric' case $p=q$ for simplicity.
- This is ofter referred to as the 'phenomenological noise model'
- A more detailed noise model would consider how the syndrome
bits are measured and how errors in that measuring circuit
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## Repeated syndrome measurements

- Repeated syndrome measurements is a good way to cope with syndrome errors.
- We can't just naively take the majority vote among the syndrome bits since additional errors can occur in between syndrome measurements, so they are not meant to agree even in the absence of syndrome errors.
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(1) Background
(2) Fault tolerance
(3) Single shot fault-tolerance?

- Random codes
- Sparse codes
- Weaker notion?

4. Conclusion

# Is it possible to do fault-tolerant quantum error correction without repeating the syndrome measurements? 

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(1) Background
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## Extra Bits



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H=\left(\begin{array}{lllllll}
1 & 0 & 1 & 0 & 1 & 0 & 1 \\
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- In general, $H \rightarrow(I \mid H)$.
- An $[n, k, d]$ code $\rightarrow$ An $\left[2 n-k, n, d^{\prime} \leq d\right]$ code.



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## Normal form

- Every parity check matrix can be put in the form $H=(I \mid A)$ for some matrix $A$ :
- Since $\mathcal{C}$ is the kernel of $H$, it does not change when we do row manipulations on $H$.
- By row manipulations (Gaussian elimination) we can put any matrix in normal form $H=(I \mid A)$.
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- Another way of deriving this upper bound is to say that
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Faulty syndrome

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I need to sober up to think about that one!

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## Summary

- Strict single-shot error correction with a phenomenological noise model is possible using random codes.
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## Summary

- Strict single-shot error correction with a phenomenological noise model is possible using random codes.
- Derived a lower bound on achievable rate.
- Upper bound depends on what counts as single-shot.
- Phenomenological noise model not justified in this setting.
- Strict single-shot error correction is not possible with sparse codes, where the phenomenological noise model is justified.
- What is the right notion of single-shot error-correction and what does it imply operationally?


