

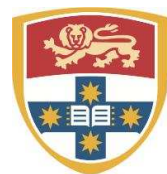
Modelling magnetic fields in the corona using nonlinear force-free fields

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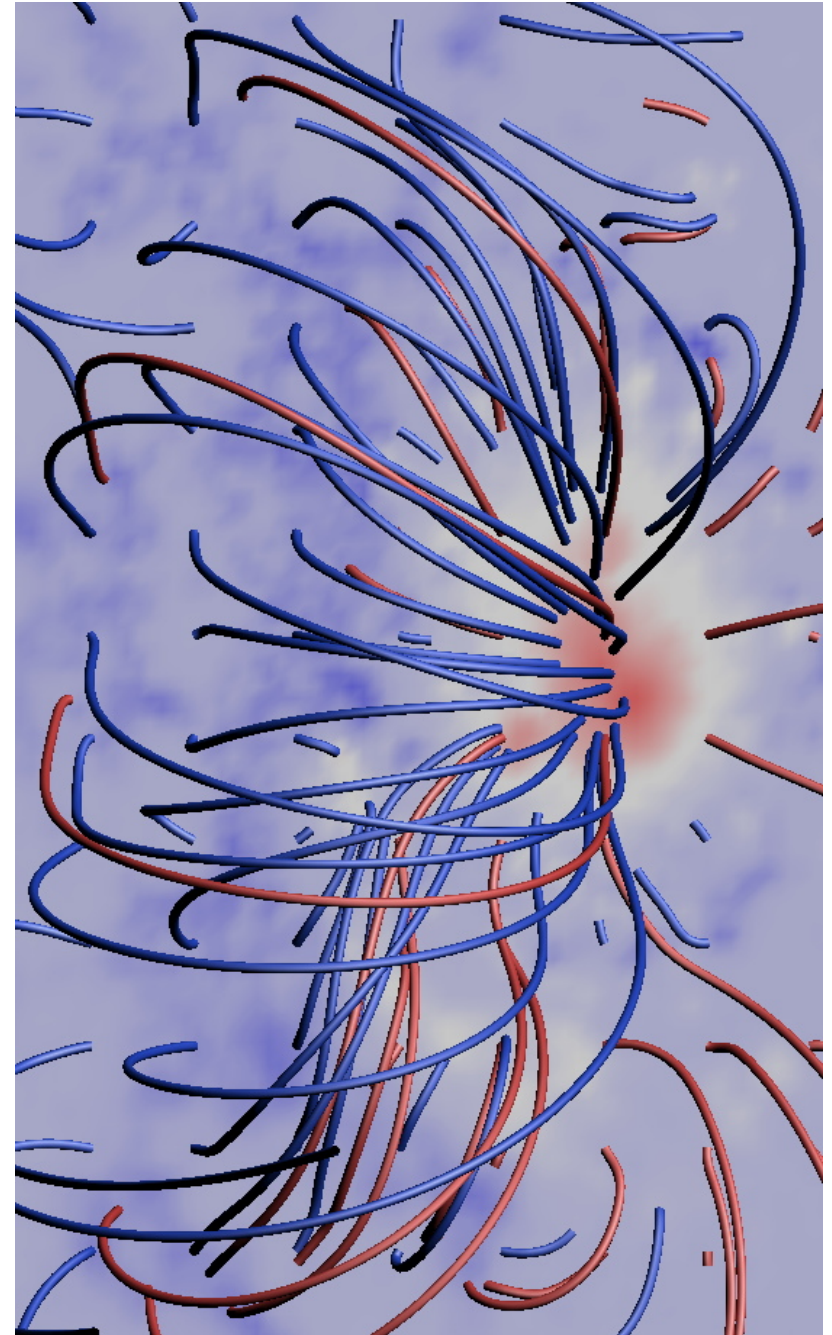
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Model for AR 10953 field (Wheatland & Leka 2011)

Overview

Background

Flares, CMEs and space weather

The data – vector magnetograms

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Modelling AR 10953 with uncertainties

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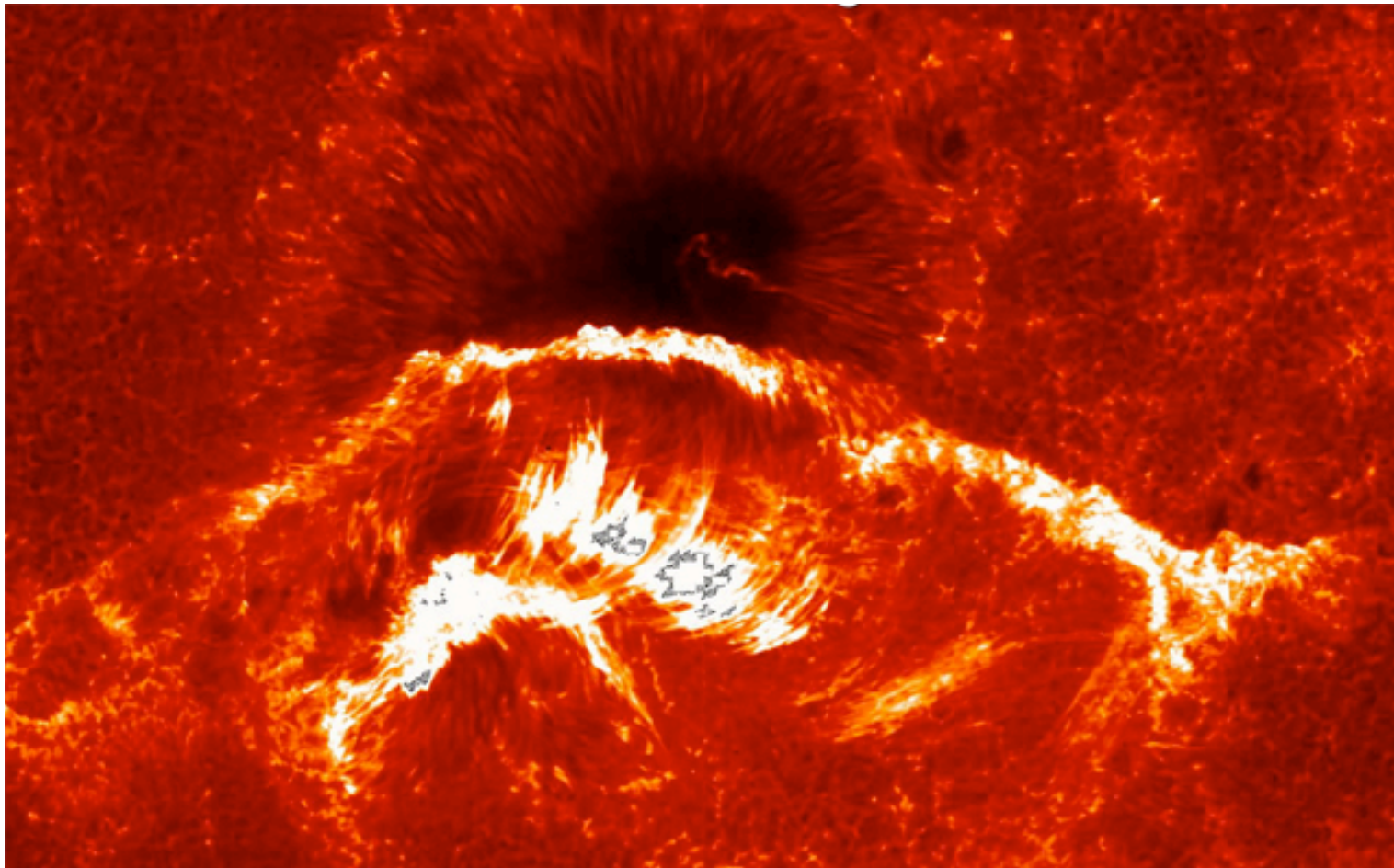
Summary

Background: Flares, CMEs and space weather

- ▶ Sunspot magnetic fields power large-scale solar activity
 - ▶ solar flares, Coronal Mass Ejections
- ▶ Space weather effects motivate modelling

(US National Research Council workshop report, Baker et al. 2008)

 - ▶ potential for large economic losses (Odenwald, Green & Taylor 2006)



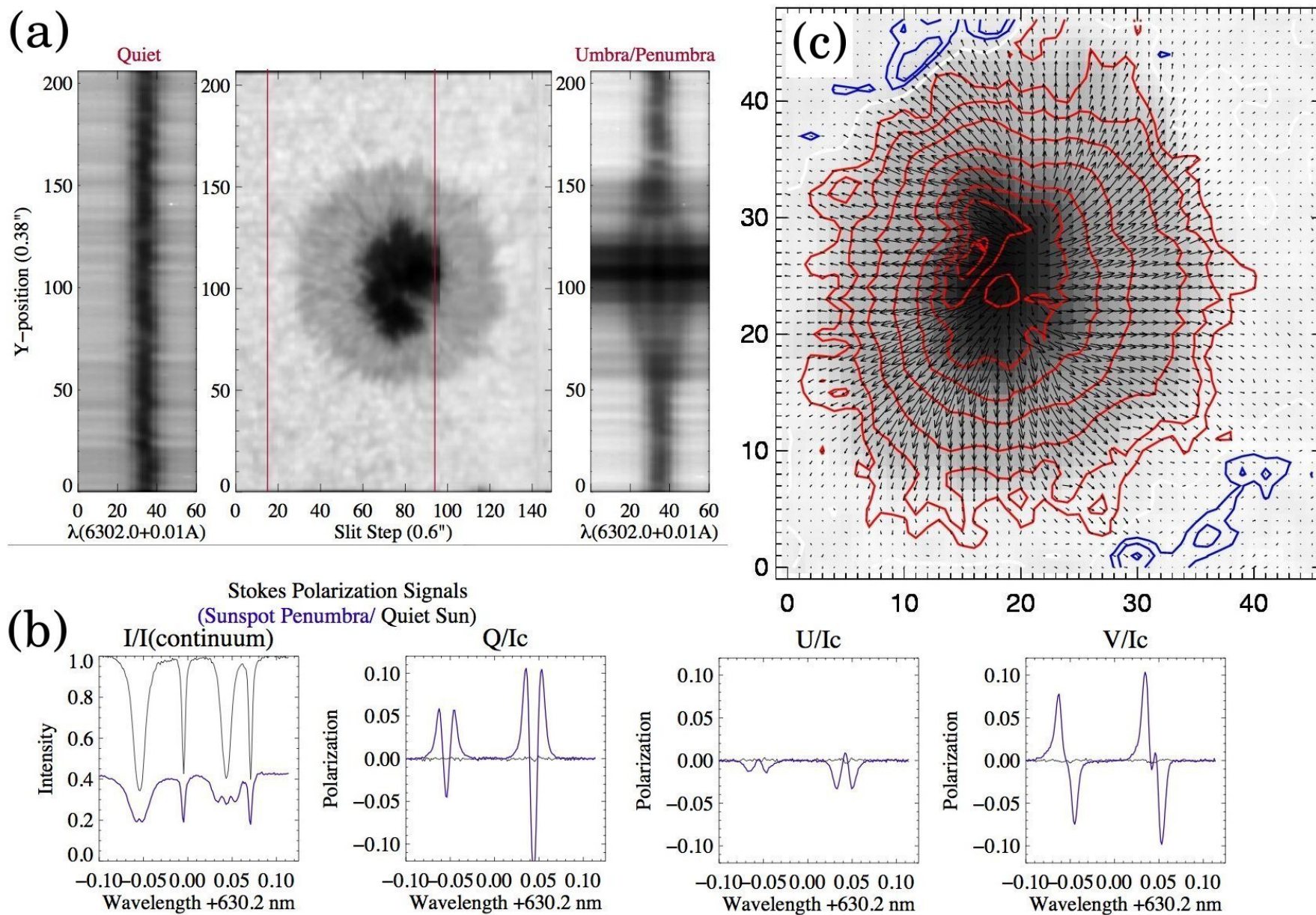
12 Dec 2006 X-class flare (Hinode/SOT)

Background: The data – vector magnetograms

Nobody can measure physical quantities of the solar atmosphere

(Del Toro Iniesta & Ruiz Cobo (1996), Sol. Phys. 164, 169)

- ▶ Zeeman effect imprints **B** on photospheric lines (del Toro Iniesta 2003)
 - ▶ Stokes polarisation profiles $I(\lambda)$, $Q(\lambda)$, $U(\lambda)$, $V(\lambda)$ measured
 - ▶ ‘Stokes inversion’ is the process of inferring magnetic field
 - ▶ an inference rather than a direct measurement/observation
- ▶ 180° ambiguity in B_\perp must be resolved
(Metcalf 1994; Metcalf et al. 2006; Leka et al. 2009)
- ▶ Vector magnetogram: photospheric map of $\mathbf{B} = (B_x, B_y, B_z)$
 - ▶ local heliocentric co-ordinates (z radially out)
 - ▶ common to neglect curvature on active region scale
- ▶ Vector magnetograms are not direct measurements/observations
 - ▶ inversion results are very method and model dependent



The data: (a) Sunspot image and line observations; (b) Stokes profiles for sunspot and quiet Sun observations; (c) vector magnetogram field values ([Advanced Stokes Polarimeter/Imaging Vector Magnetograph](#))

- ▶ In principle, VMs give BCs for coronal field modelling
 - ▶ referred to as coronal magnetic field **reconstruction**
- ▶ Vertical current density J_z may be estimated at photosphere:

$$\mu_0 J_z|_{z=0} = \left. \frac{\partial B_y}{\partial x} \right|_{z=0} - \left. \frac{\partial B_x}{\partial y} \right|_{z=0} \quad (1)$$

- ▶ New generation of instruments
 - ▶ US NSO Synoptic Long-term Investigations of the Sun Vector Spectro-magnetograph (SOLIS/VSM)
([Jones et al. 2002](#))
 - ▶ Hinode Solar Optical Telescope Spectro-Polarimeter (SOT/SP)
([Tsuneta et al. 2008](#))
 - ▶ Solar Dynamics Observatory Helioseismic & Magnetic Imager (SDO/HMI) ([Scherrer et al. 2006](#))

Background: Nonlinear force-free modelling

- ▶ Force-free model for coronal magnetic field:

$$\mathbf{J} \times \mathbf{B} = 0 \quad \text{and} \quad \nabla \cdot \mathbf{B} = 0 \quad (2)$$

- ▶ $\mathbf{J} = \mu_0^{-1} \nabla \times \mathbf{B}$ is electric current density
 - ▶ physics: static model in which Lorentz force dominates
 - ▶ coupled nonlinear PDEs
- ▶ Writing $\mathbf{J} = \alpha \mathbf{B} / \mu_0$ (\mathbf{J} is parallel to \mathbf{B}):

$$\mathbf{B} \cdot \nabla \alpha = 0 \quad \text{and} \quad \nabla \times \mathbf{B} = \alpha \mathbf{B} \quad (3)$$

- ▶ α is the force-free parameter

- ▶ Boundary conditions: (Grad & Rubin 1958)
 - ▶ B_z over $z = 0$
 - ▶ α over $z = 0$ where $B_z > 0$ or where $B_z < 0$
 - ▶ over one polarity
 - ▶ we refer to the polarities as P and N respectively
- ▶ Vector magnetograms give two sets of boundary conditions
 - ▶ values of $\alpha = \mu_0 J_z / B_z$ over both P and N are available
- ▶ Methods of solution of Eqs. (3) are iterative (e.g. Wiegelmann 2008)
- ▶ Current-field iteration/Grad-Rubin iteration (Grad & Rubin 1958)
 - ▶ at iteration k solve the linear system

$$\mathbf{B}^{[k-1]} \cdot \nabla \alpha^{[k]} = 0 \quad \text{and} \quad \nabla \times \mathbf{B}^{[k]} = \alpha^{[k]} \mathbf{B}^{[k-1]} \quad (4)$$

- ▶ BCs imposed on $B_z^{[k]}$ and on $\alpha^{[k]}$ over P or N

Background: The inconsistency problem

- ▶ Force-free methods work for test cases but **fail for solar data**

(Schrijver et al. 2006; Metcalf et al. 2008; Schrijver et al. 2008; DeRosa et al. 2009)

- ▶ different methods give different fields
- ▶ **P and N solutions do not agree** for a Grad-Rubin method
- ▶ some force-free methods use $\mathbf{B}|_{z=0}$ as BCs
(Wheatland, Sturrock & Roumeliotis 2000; Wiegelman 2000)

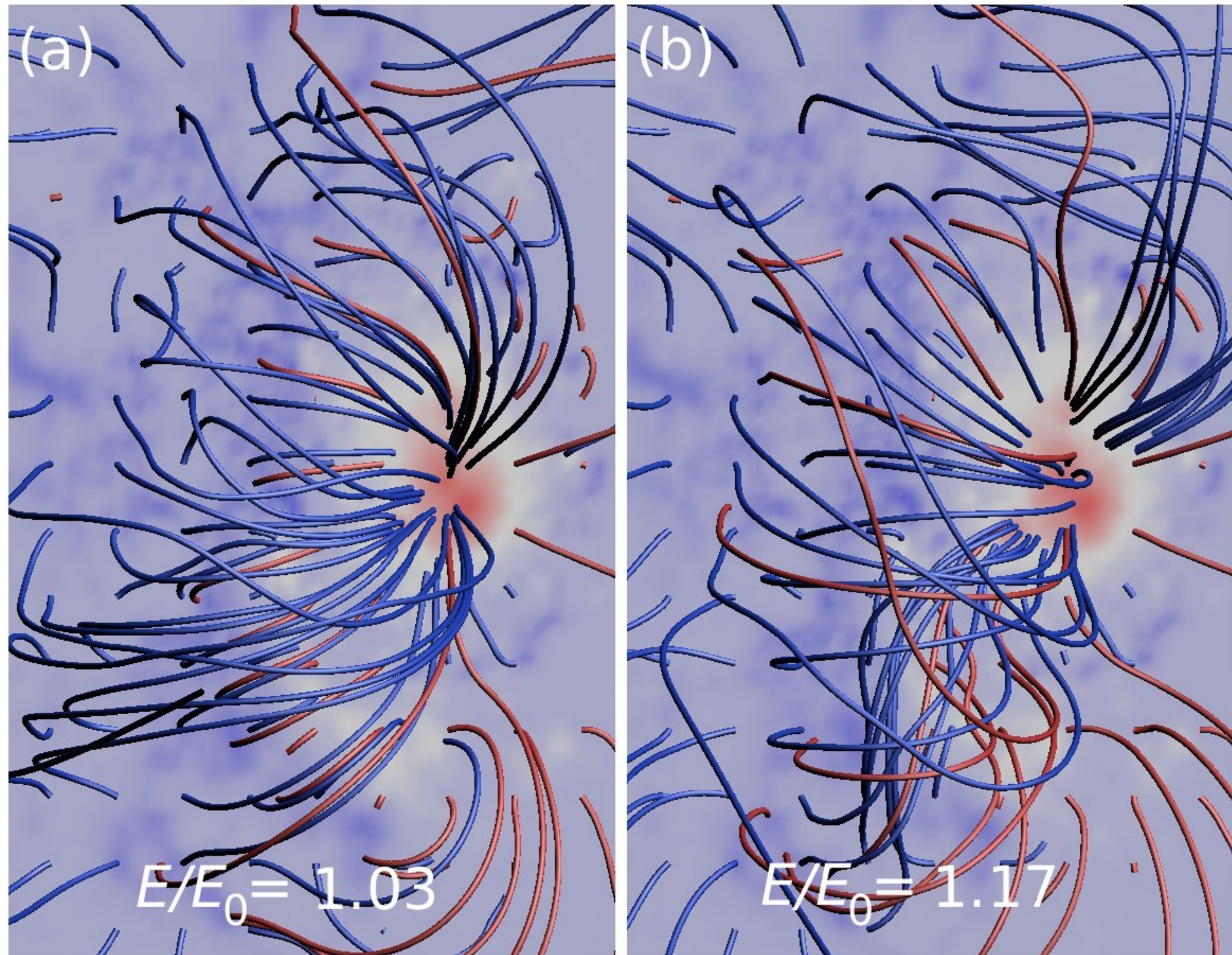
- ▶ the 'solutions' have $\mathbf{J} \times \mathbf{B} \neq 0$ and/or $\nabla \cdot \mathbf{B} \neq 0$
- ▶ they **fail to solve the model**

- ▶ Vector magnetogram BCs **inconsistent with force-free model**

- ▶ errors in measurements and field inference
- ▶ field at photospheric level is not force free (Metcalf et al. 1995)
- ▶ necessary conditions for a force-free field **are not met**
(Molodenskii 1969)

- ▶ **Force-free models from vector magnetograms are unreliable**

► Illustration of the problem: AR 10953 on 30 June 2007



Inconsistent solutions from vector magnetogram BCs: (a) *P* solution; (b) *N* solution (Wheatland & Leka 2011)

- ▶ One approach to the problem is 'preprocessing' (Wiegelmann et al. 2006)
 - ▶ BCs modified to satisfy necessary force-free conditions...
 - ▶ ...but they are necessary, not sufficient
 - ▶ preprocessed BCs are inconsistent with the force-free model (DeRosa et al. 2009)
 - ▶ this procedure typically also smooths, which is undesirable
- ▶ Alternative approach:
 - ▶ find the 'closest' force-free solution to the observed data

Background: Self-consistency recipe (Wheatland & Régnier 2009)

1. Calculate P and N solutions using Grad-Rubin (Wheatland 2006; 2007)

- ▶ BCs: unprocessed vector magnetogram data

2. Adjust boundary values using solutions and uncertainties

- ▶ Each solution has α constant along \mathbf{B} ...

- ▶ ...so they define two sets of α values at $z = 0$:

$$\alpha_P \pm \sigma_P \quad \text{and} \quad \alpha_N \pm \sigma_N \quad (5)$$

- ▶ Each is **consistent** with the force-free model

- ▶ Bayesian probability is used to estimate 'true' values:

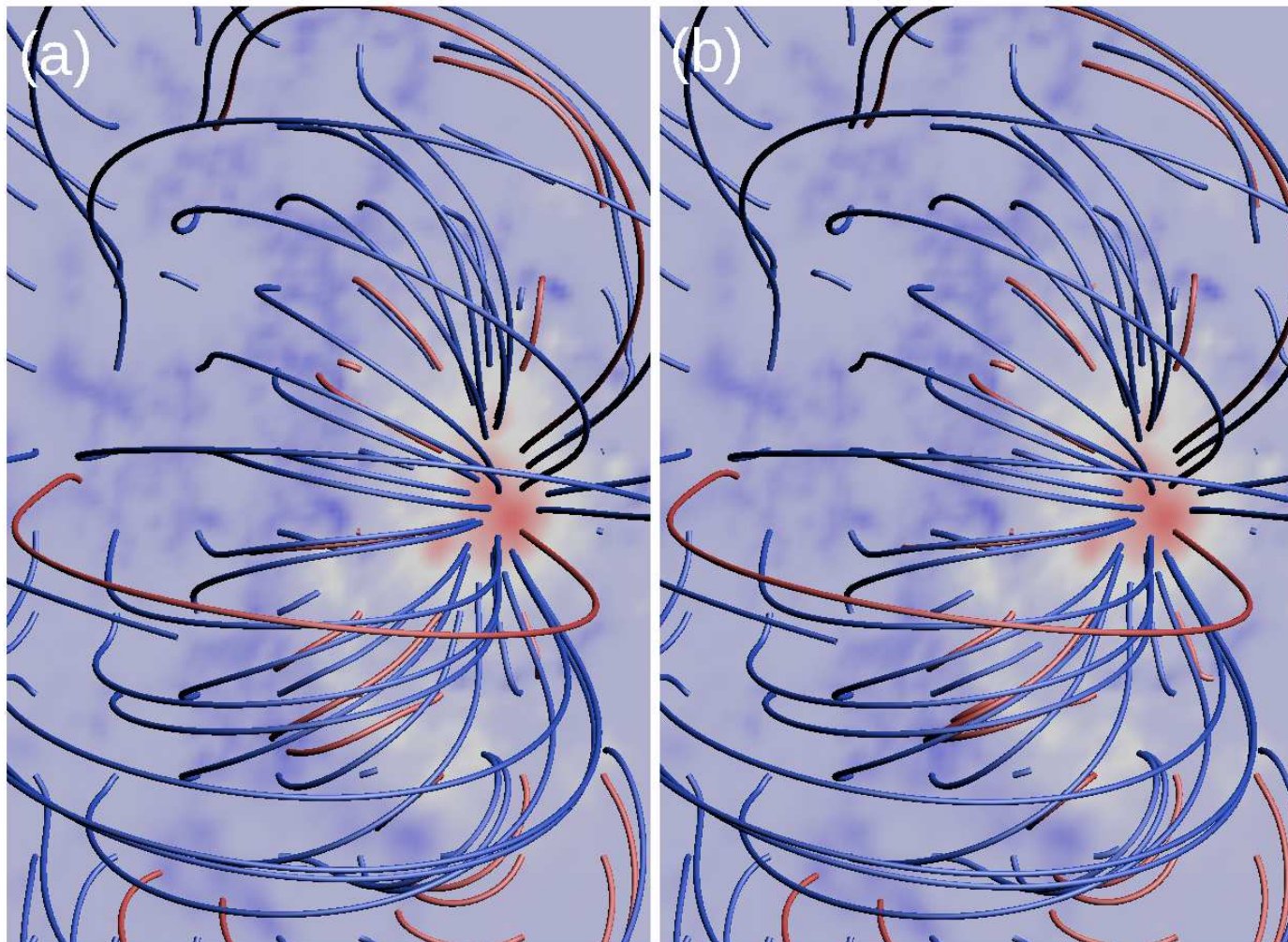
$$\alpha_{\text{est}} = \frac{\alpha_P / \sigma_P^2 + \alpha_N / \sigma_N^2}{1 / \sigma_P^2 + 1 / \sigma_N^2} \quad \sigma_{\text{est}} = \left(1 / \sigma_P^2 + 1 / \sigma_N^2 \right)^{-\frac{1}{2}} \quad (6)$$

- ▶ Still inconsistent but **closer** to consistency

3. Iterate 1. & 2. until P and N solutions agree (α_{est} consistent)

- ▶ Step 1. uses α_{est} for BCs at subsequent iterations

- ▶ Initial test on AR 10953 (Wheatland & Régnier 2009)
 - ▶ method shown to work: a ‘proof of concept’
 - ▶ but uncertainties not included
 - ▶ self-consistent solution near to potential
 - ▶ energy $E/E_0 = 1.02$ (potential field energy is E_0)

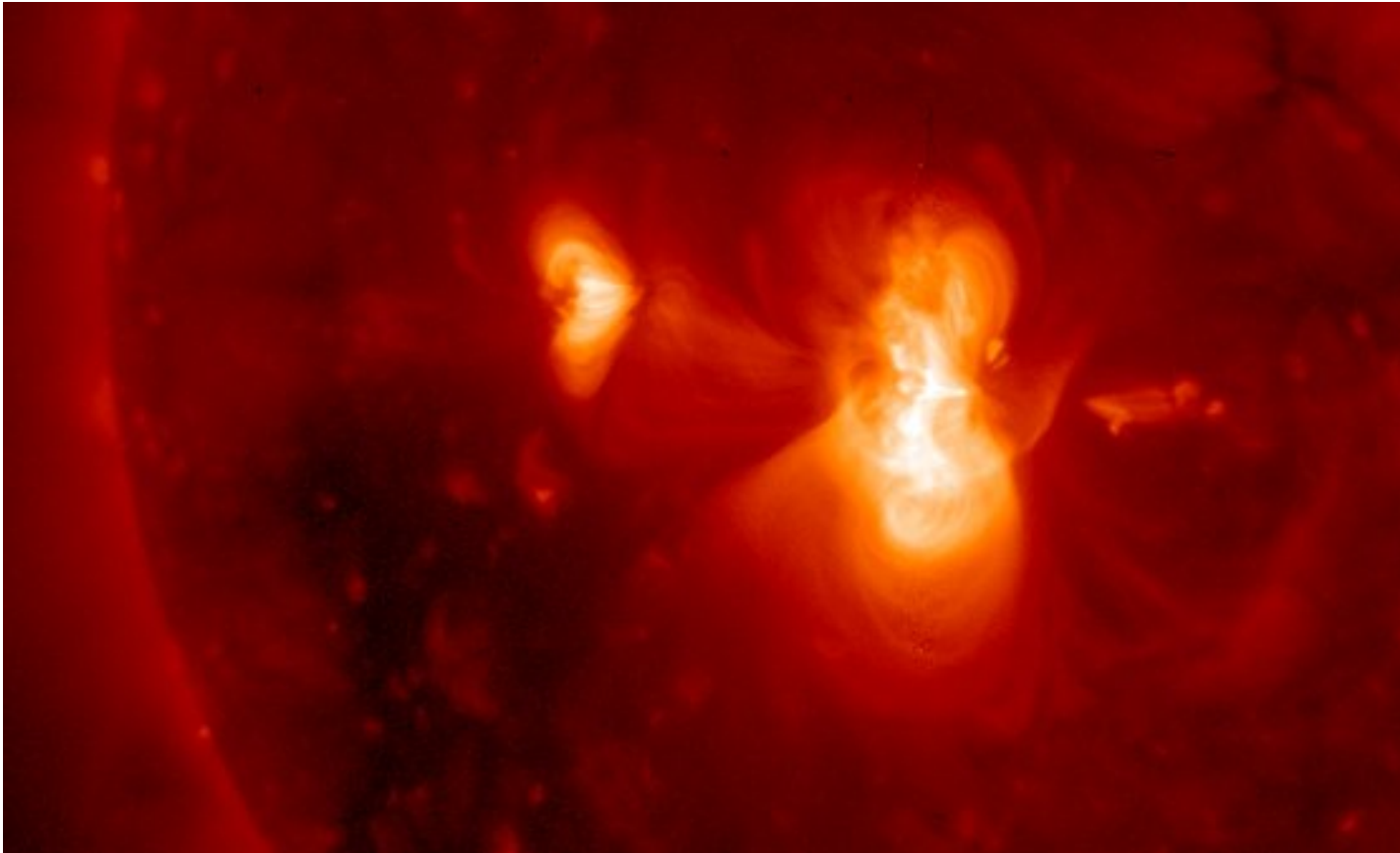


Self-consistent P (left) and N (right) solutions for AR 10953 (Wheatland & Régnier 2009)

Modelling AR 10953 with uncertainties: Data

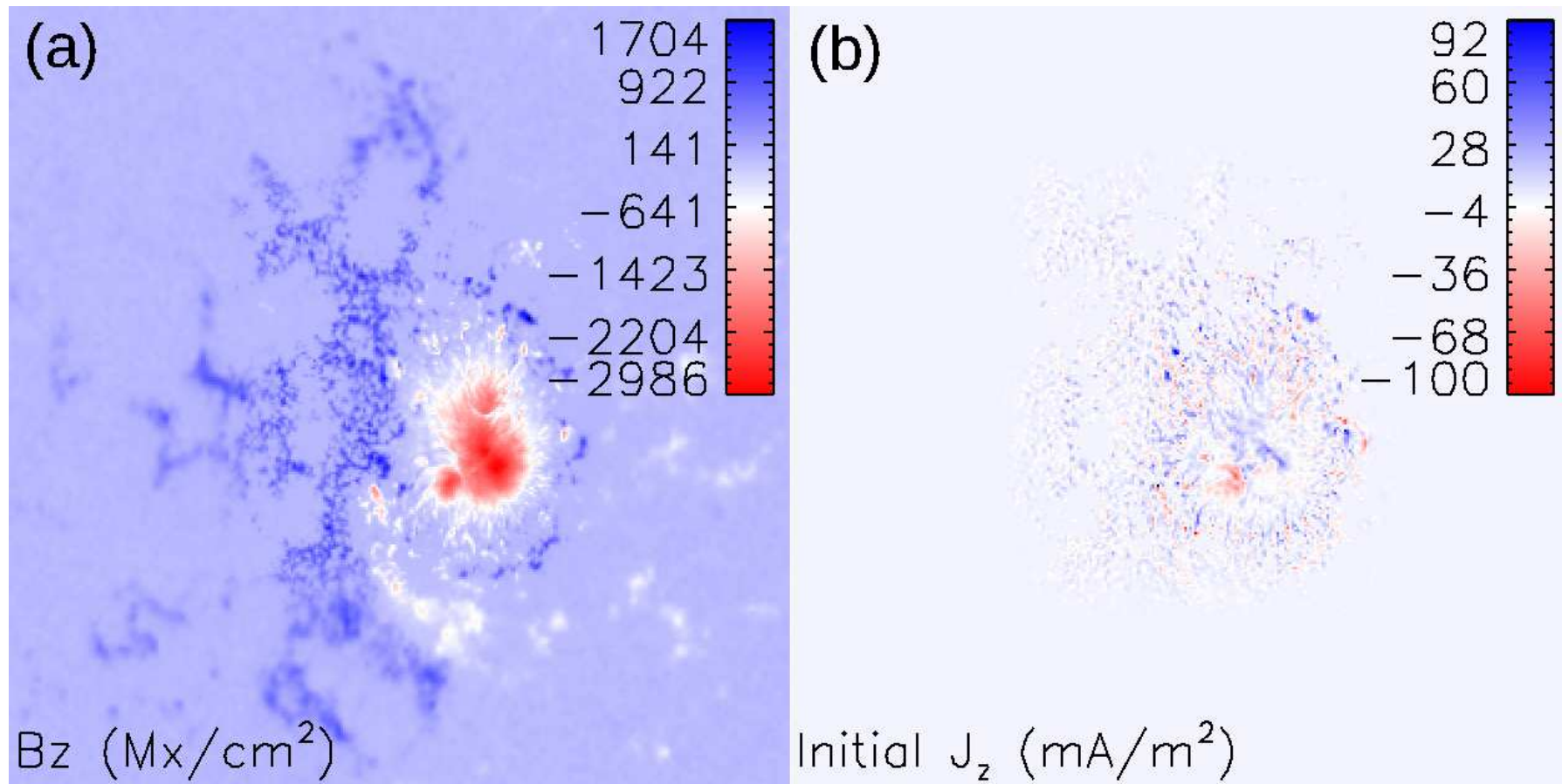
(Wheatland & Leka 2011)

- ▶ AR 10953 on 30 April 2007 is again the region of study
 - ▶ many force-free methods applied before (De Rosa et al. 2009)
 - ▶ self-consistent modelling test case (Wheatland & Régnier 2009)
- ▶ Hinode SOT/SP and MDI data used
 - ▶ new treatment: improved data merging and **uncertainties**

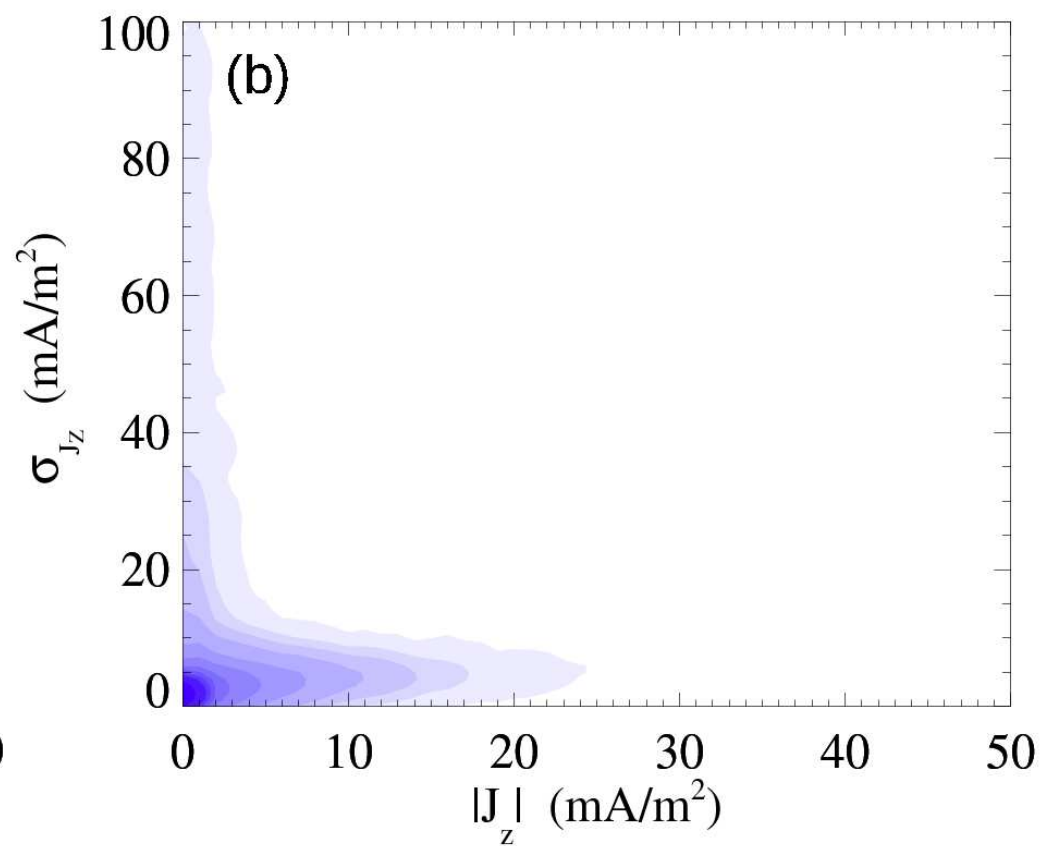
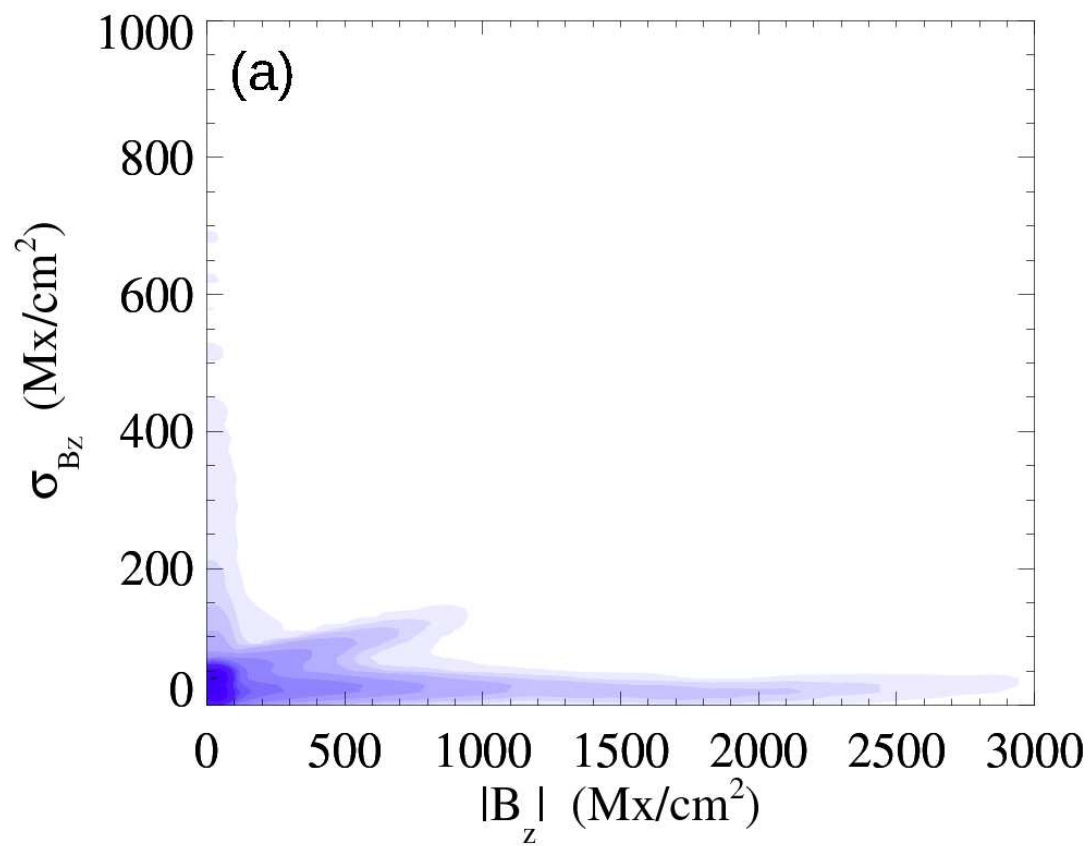


Hinode/XRT broadband soft X-ray image (Hinode/XRT)

- ▶ MDI data used to provide a wider FOV
- ▶ Uncertainties derived from Stokes inversion fit: ‘lower limits’
- ▶ Boundary values $\alpha_0 \pm \sigma_0$ calculated from $B_i \pm \sigma_{B_i}$
 - ▶ points in MDI region assigned maximal uncertainties



Vector magnetogram B_z values (left) and J_z values (right) (Wheatland & Leka 2011)

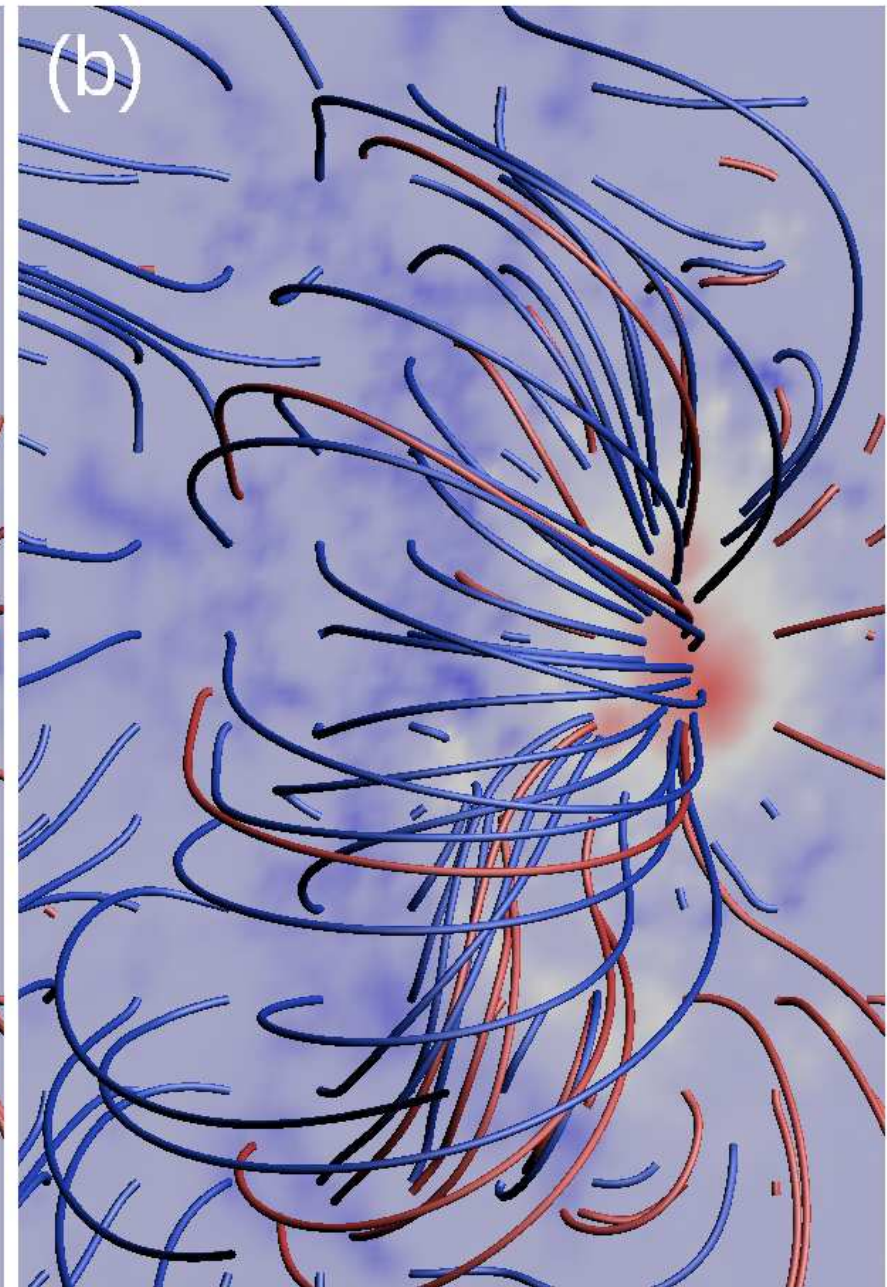
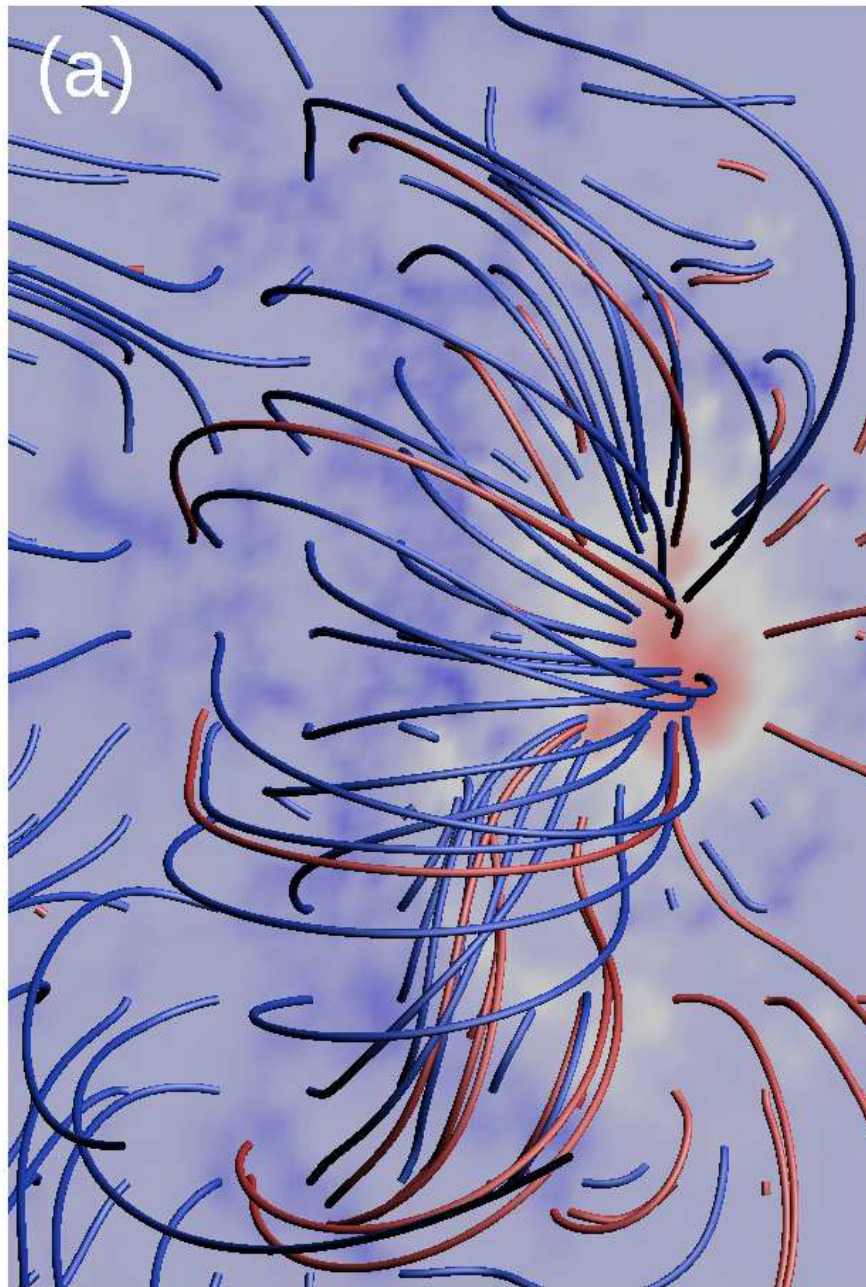


Vector magnetogram B_z values (left) and J_z values (right) ([Wheatland & Leka 2011](#))

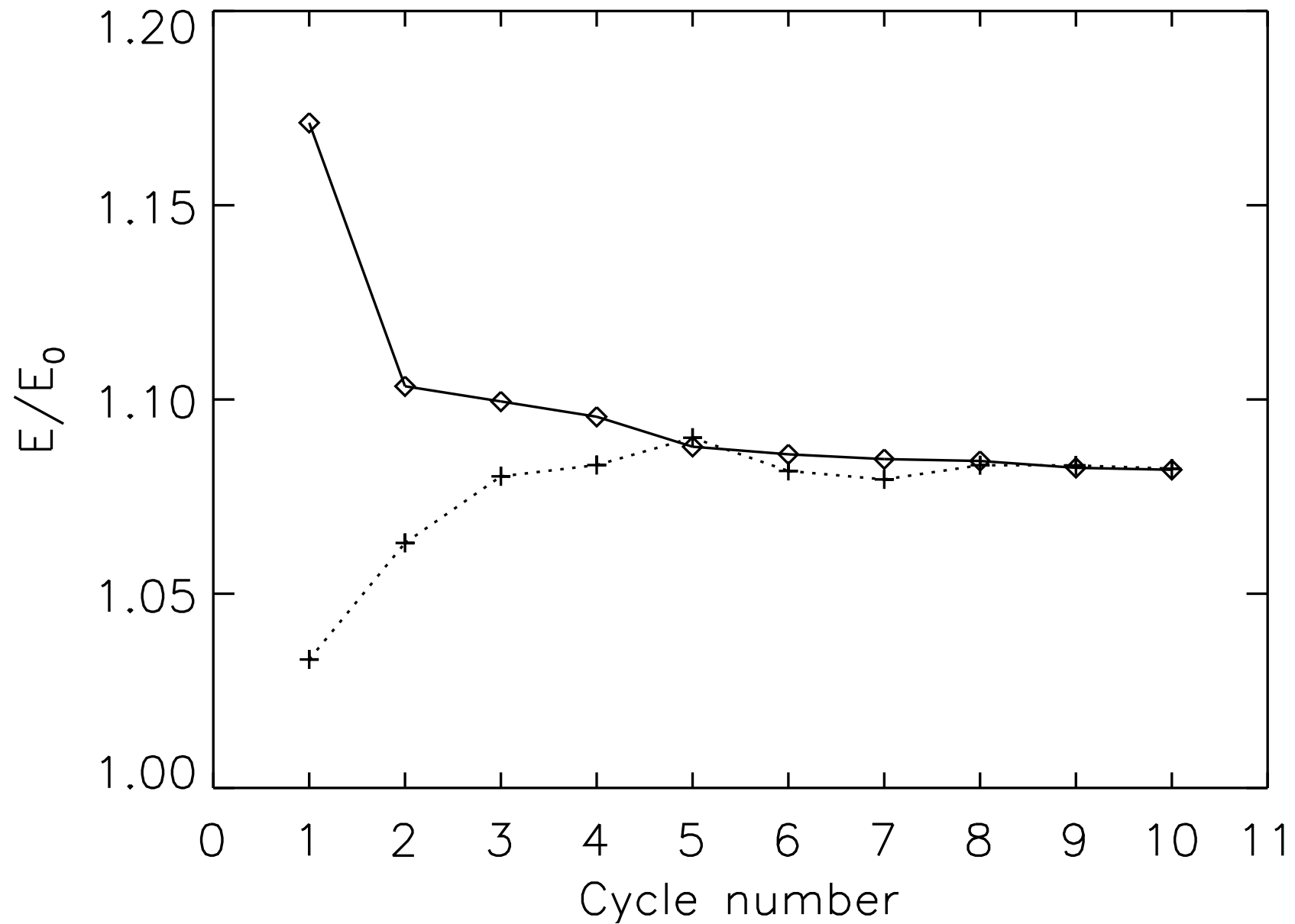
Modelling AR 10953 with uncertainties: Results

(Wheatland & Leka 2011)

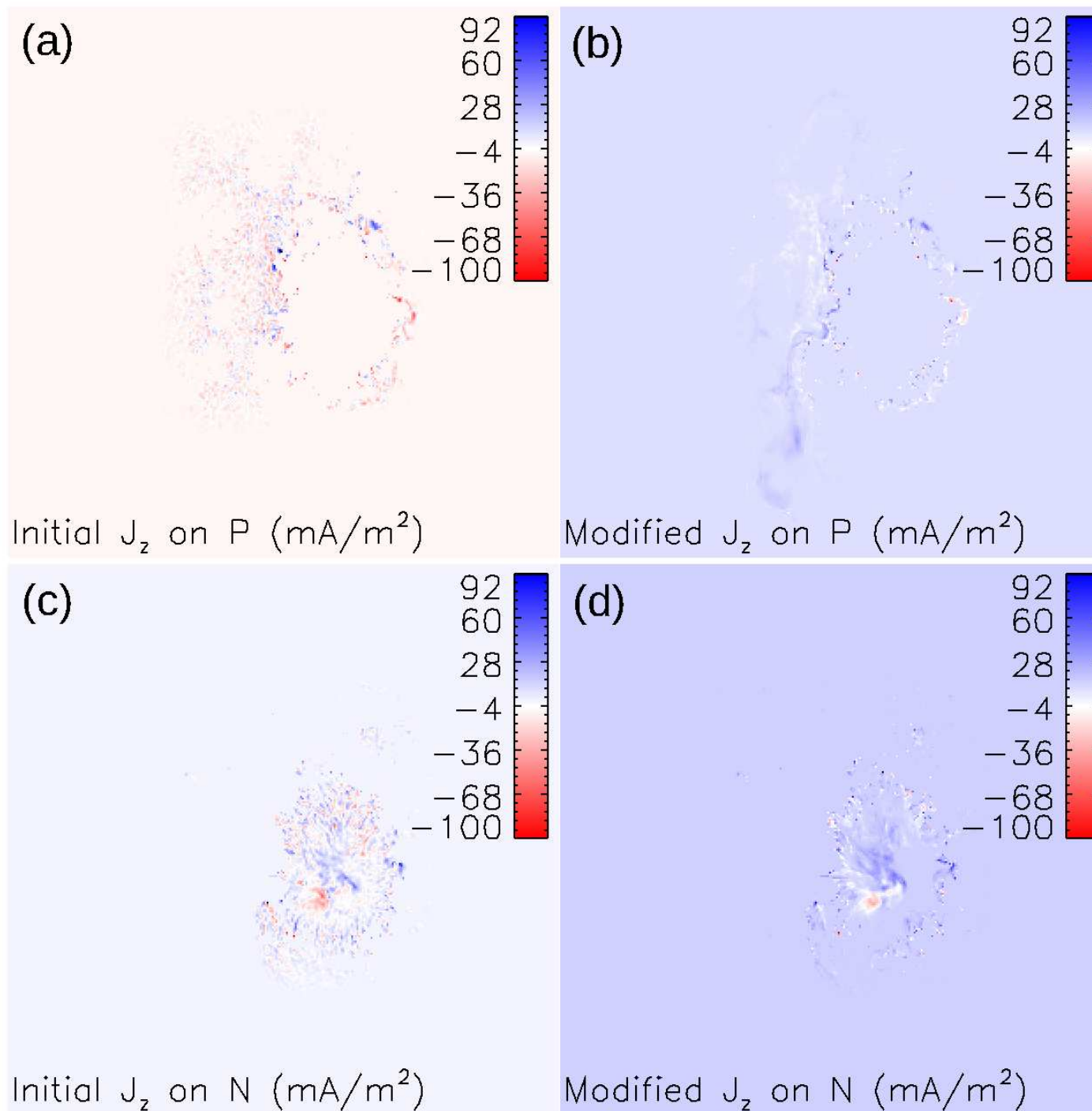
- ▶ 10 self consistency cycles used
 - ▶ grid size is $313 \times 313 \times 300$ (spacing is 0.8 arcsec)
 - ▶ $N_{GR} = 30$ Grad-Rubin iterations per cycle
 - ▶ currents crossing side and top boundaries omitted (Wheatland 2007)
- ▶ Procedure converges in < 10 cycles
 - ▶ energy of final solution(s) is $E/E_0 = 1.08$
 - ▶ significantly non-potential
 - ▶ energies of P and N solutions differ by $< 0.03\%$
 - ▶ self-consistency is achieved
- ▶ B_x and B_y are modified by self-consistency procedure
 - ▶ the changes exceed the nominal uncertainties
 - ▶ but are similar to those imposed by preprocessing
 - ▶ this implies the initial data are quite inconsistent
- ▶ BCs on α are preserved at locations with small σ
 - ▶ attention is paid to the most believable inference



Self-consistent solutions: (a) P solution; (b) N solution ([Wheatland & Leka 2011](#))

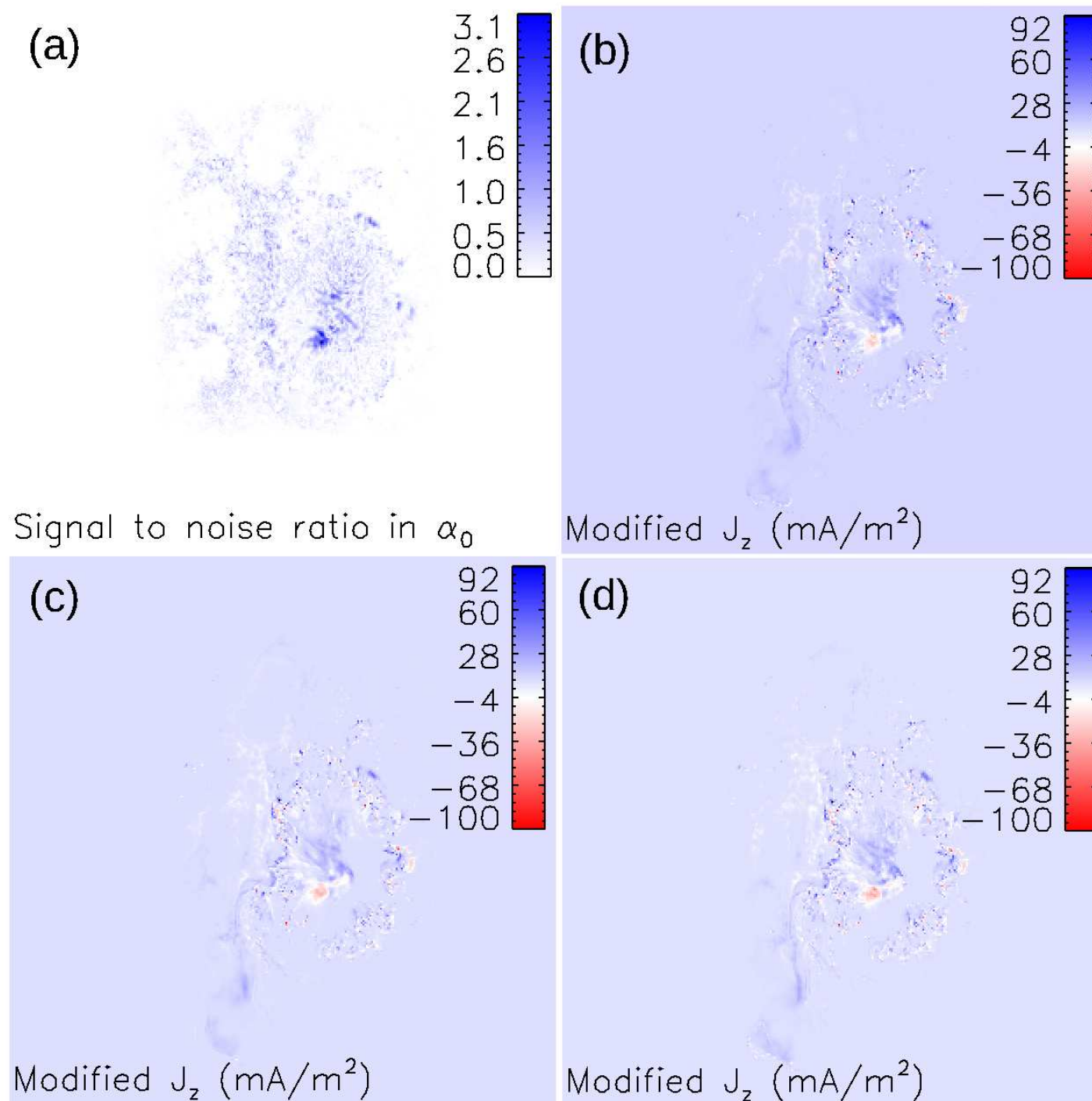


Energy of P solution (+) and N solution (◇) versus self-consistency cycle ([Wheatland & Leka 2011](#))



Initial BCs on J_z (left column) and self-consistent values (right column) (Wheatland & Leka 2011)

- ▶ Grad-Rubin iteration does not converge strictly initially
 - ▶ but oscillates in energy (another symptom of inconsistency)
 - ▶ which introduces some arbitrariness in the modelling
 - ▶ a dependence on the number N_{GR} of GR iterations
- ▶ Modelling repeated with $N_{GR} = 20$ and $N_{GR} = 40$
 - ▶ results very similar which suggests the process is robust
 - ▶ energies of two new solutions are $E/E_0 = 1.08$ to 1 s.f.
 - ▶ minor differences in final BCs and field structure
- ▶ Energy of solution is higher when uncertainties are included
 - ▶ large J_z values in strong field regions have small σ
 - ▶ these values are preserved giving higher E
- ▶ Energy $E/E_0 = 1.08$ is between initial N and P energies
 - ▶ in the range of energies found in other studies
(de Rosa et al. 2009; Canou & Amari 2010)
 - ▶ higher GR-method energies in other studies are the N solution
 - ▶ the P solution is ignored (e.g. Canou & Amari 2010)



Signal to noise ratio in α_0 and the BCs on J_z for the solutions with $N_{GR} = 20, 30, 40$ (Wheatland & Leka 2011)

Summary

- ▶ Vector magnetograms give BCs for coronal field modelling
 - ▶ the field values are **inferences** not measurements
 - ▶ the modelling is difficult
- ▶ The nonlinear force-free model is popular
 - ▶ but vector magnetogram data are inconsistent with the model
 - ▶ **nonlinear force-modelling gives unreliable results**
 - ▶ the **self-consistency procedure** provides one solution
- ▶ Self-consistency modelling for AR 10953
 - ▶ relative uncertainties in boundary data accounted for
 - ▶ significantly non-potential force-free model field obtained
 - ▶ results robust against different choices in the method
- ▶ Self-consistency is a promising method
 - ▶ however more physical modelling should be pursued